- suppose that you take a measurement x<sub>1</sub> of some real-valued quantity (distance, velocity, etc.)
- your friend takes a second measurement x<sub>2</sub> of the same quantity
- after comparing the measurements you find that

 $x_1 \neq x_2$ 

• what is the best estimate of the true value  $\mu$ ?

 suppose that an appropriate noise model for the measurements is

$$x_1 = x + \varepsilon_{\sigma^2}$$
$$x_2 = x + \varepsilon_{\sigma^2}$$

where  $\mathcal{E}_{\sigma^2}$  is zero-mean Gaussian noise with variance  $\sigma^2$ 

because two different people are performing the measurements it might be reasonable to assume that x<sub>1</sub> and x<sub>2</sub> are independent

```
x = 5;
x1 = x + randn(1, 1000); % noise variance = 1
x2 = x + randn(1, 1000); % noise variance = 1
mu2 = (x1 + x2) / 2;
```

```
bins = 1:0.2:9;
hist(x1, bins);
hist(x2, bins);
hist(mu2, bins);
```



var(x1) = 0.9979

var(x2) = 0.9972

5



var(mu2) = 0.4942

- suppose the precision of your measurements is much worse than that of your friend
- consider the measurement noise model

$$x_1 = x + 3\varepsilon_{\sigma^2}$$
$$x_2 = x + \varepsilon_{\sigma^2}$$

where  $\varepsilon_{\sigma^2}$  is zero-mean Gaussian noise with variance  $\sigma^2$ 

```
x = 7;
x1 = x + 3 * randn(1, 1000); % noise variance = 3*3 = 9
x^2 = x + randn(1, 1000); % noise variance = 1
mu2 = (x1 + x2) / 2;
```

bins = -2:0.2:18;hist(x1, bins); hist(x2, bins); hist(mu2, bins);



var(x1) = 8.9166

var(x2) = 0.9530



is the average the optimal estimate of the combined measurements?

instead of ordinary averaging, consider a weighted average

$$\mu = \omega_1 x_1 + \omega_2 x_2$$

where  $\omega_1 + \omega_2 = 1$ 

the variance of a random variable is defined as

$$var(X) = E[(X - E[X])^2]$$

where E[X] is the expected value of X

### Expected Value

- informally, the expected value of a random variable X is the long-run average observed value of X
- formally defined as

$$\mathrm{E}[X] = \int_{-\infty}^{\infty} x f(x) \, dx$$

properties

$$E[c] = c$$
  

$$E[E[X]] = E[X]$$
  

$$E[X + c] = E[X] + c$$
  

$$E[X + Y] = E[X] + E[Y]$$
  

$$E[cX] = cE[X]$$
  

$$E[XY] = E[X]E[Y] \text{ if } X \text{ and } Y \text{ are independent}$$

$$\operatorname{var}(\mu) = \operatorname{E}[(\mu - \operatorname{E}[\mu])^{2}]$$
  
=  $\operatorname{E}[(\omega_{1}x_{1} + \omega_{2}x_{2} - \operatorname{E}[\omega_{1}x_{1} + \omega_{2}x_{2}])^{2}]$   
= ...  
=  $\omega_{1}^{2}\sigma_{1}^{2} + \omega_{2}^{2}\sigma_{2}^{2} + 2\omega_{1}\omega_{2}\operatorname{E}[(x_{1} - \operatorname{E}[x_{1}])(x_{2} - \operatorname{E}[x_{2}])]$ 

• because  $x_1$  and  $x_2$  are independent

$$(x_1 - E[x_1])$$
 and  $(x_2 - E[x_2])$ 

are also independent; thus

$$E[(x_1 - E[x_1])(x_2 - E[x_2])] = 0$$

finally

$$\operatorname{var}(\mu) = \omega_1^2 \sigma_1^2 + \omega_2^2 \sigma_2^2$$

• because  $x_1$  and  $x_2$  are independent

$$(x_1 - E[x_1])$$
 and  $(x_2 - E[x_2])$ 

are also independent; thus

$$E[(x_1 - E[x_1])(x_2 - E[x_2])] = 0$$

finally

$$\operatorname{var}(\mu) = \omega_1^2 \sigma_1^2 + \omega_2^2 \sigma_2^2$$
$$= (1 - \omega^2) \sigma_1^2 + \omega^2 \sigma_2^2 \quad \text{where} \quad \omega_2 = \omega, \quad \omega_1 = 1 - \omega$$

one way to choose the weighting values is to choose the weights such that the variance is minimized

$$\frac{d}{d\omega} \operatorname{var}(\mu) = 0 = -2(1-\omega)\sigma_1^2 + 2\omega\sigma_2^2$$
$$\sigma_1^2$$

 $\Rightarrow \omega = \frac{\sigma_1}{\sigma_1^2 + \sigma_2^2}$ 

#### Minimum Variance Estimate

thus, the minimum variance estimate is



x = 7; x1 = x + 3 \* randn(1, 1000); % noise variance = 3\*3 = 9 x2 = x + randn(1, 1000); % noise variance = 1 w = 9 / (9 + 1); mu2 = (1 - w) \* x1 + w \* x2; bins = -2:0.2:18; hist(x1, bins); hist(x2, bins); hist(x2, bins);

### Minimum Variance Estimate

mu2=0.5\*x1 + 0.5\*x2

mu2=0.1\*x1 + 0.9\*x2



var(mu2) = 2.4317

var(mu2) = 0.8925